

# Pthreads (POSIX Threads)

- a POSIX standard (IEEE 1003.1c) API for user thread creation and synchronization.
- API specifies behavior of the thread library, implementation is up to development of the library.
- Common in UNIX operating systems, but not in Windows.

# Pthread commands

- The `pthread_create` function creates a new thread. It takes four arguments:
  - a thread variable or holder for the thread,
  - a thread attribute,
  - the function for the thread to call when it starts execution, and
  - an argument to the function. For example:

```
pthread_t          a_thread;
pthread_attr_t     a_thread_attribute;
void               thread_function(void *argument);
char               *some_argument;
pthread_create( &a_thread,
               a_thread_attribute,
               (void *)&thread_function,
               (void *)&some_argument);
```

From [http://dis.cs.umass.edu/~wagner/threads\\_html/tutorial.html](http://dis.cs.umass.edu/~wagner/threads_html/tutorial.html)

# Pthread Creation

- All Pthread programs must include the `pthread.h` header file
- `Pthread_t pid` declares the thread identifier
- A thread has a set of attributes set by the `pthread_attr_t attr` declaration, with `pthread_attr_init(&attr)`
- The thread itself is created with `pthread_create(&pid, &attr, &func, &args)` where `func(args)` is a function to be run in the new thread.

# Pthread example code

```
#include <pthread.h>
#include <stdio.h>

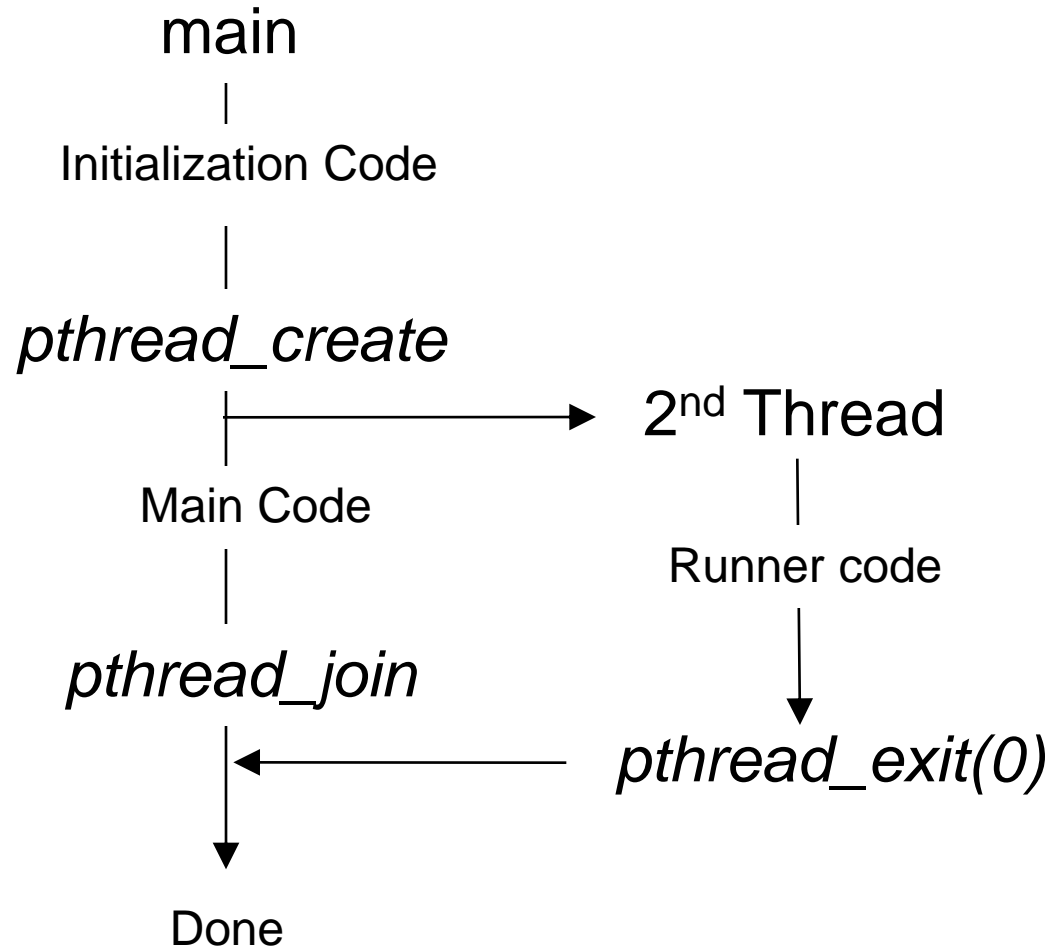
int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* the thread */

main(int argc, char *argv[])
{
    pthread_t tid;          /* the thread identifier */
    pthread_attr_t attr; /* set of thread attributes */
    if (argc != 2) {
        fprintf(stderr, "usage: a.out <integer value>\n");
        exit();
    }
    if (atoi(argv[1]) < 0) {
        fprintf(stderr, "%d must be >= 0\n" ,atoi(argv[1])) ;
        exit();          /* atoi converts string to integer*/
    }
}
```

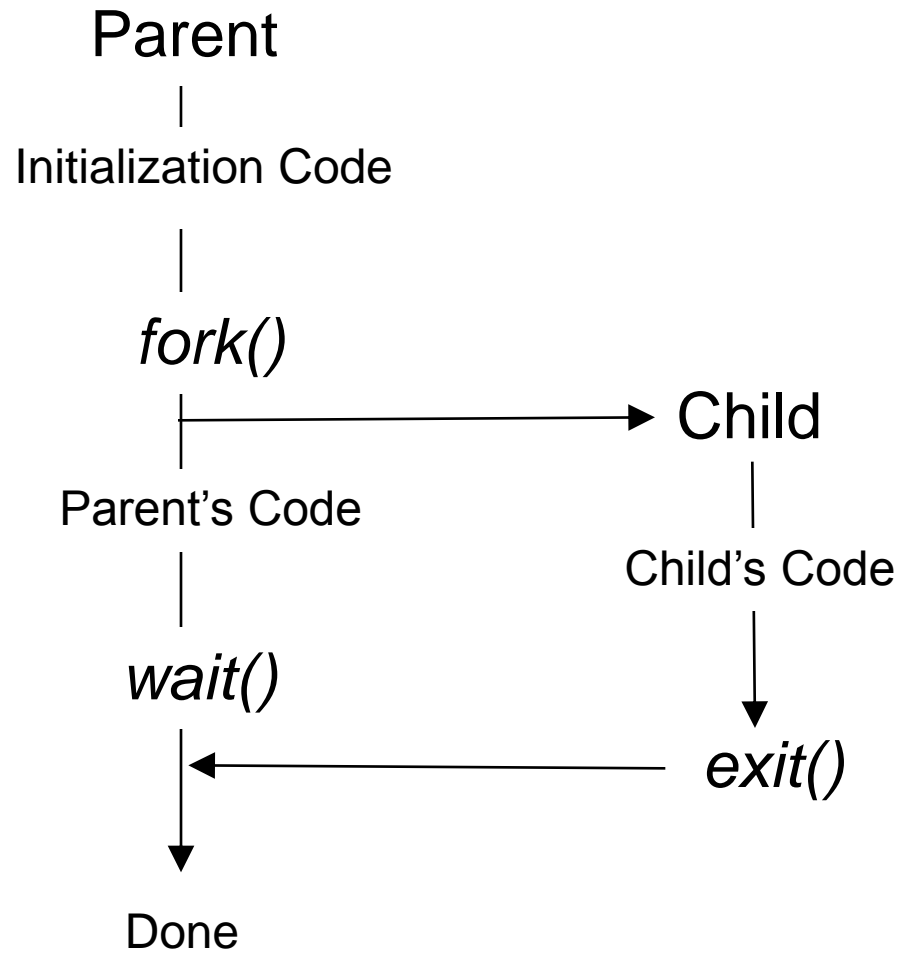
# Pthread example code

```
/* get the default attributes */
pthread_attr_init(&attr) ;
/* create the thread */
pthread_create (&tid, &attr, runner, argv[1]);
/* now wait for the thread to exit */
pthread_join (tid, NULL) ;
printf("sum = %d\n",sum);
}
/* The thread will begin control in this function */
void *runner(void *param)
{
    int upper = atoi(param);
    int i;
    sum = 0;
    if (upper > 0) {
        for (i = 1; i <= upper; i++)
            sum += i;
    }
    pthread_exit(0);
}
```

# The thread process



# The fork process



# Thread Attributes

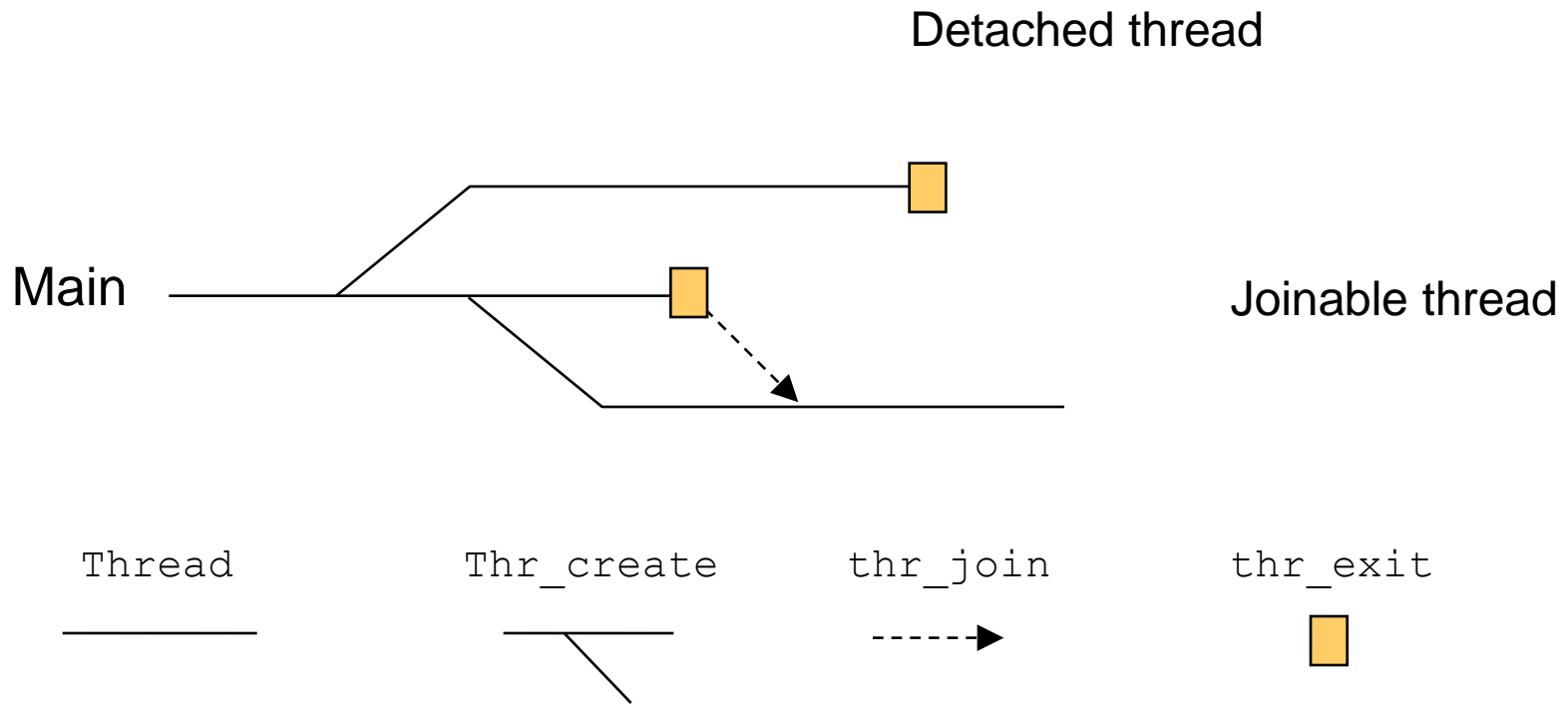
- Scope
  - The scope may be process-wide or system-wide
  - After creating an attribute object (eg. attr), the scope is set by `pthread_attr_setscope()`
  - If scope is defined `PTHREAD_SCOPE_SYSTEM`, then the thread is “bound” and the kernel can “see” the thread.
  - If scope is defined `PTHREAD_SCOPE_PROCESS`, then the thread is “unbound” and the kernel does not see the thread (default).



# Thread Attributes

- Detach State
  - The detach state determines if the thread will be joinable from another thread.
  - After creating an attribute object (eg. attr), the detach state is set by `pthread_attr_setdetachstate()`
  - If detach state is defined `PTHREAD_CREATE_DETACHED`, then the thread is “detached” and the thread resources will be discarded on termination.
  - If detach state is defined `PTHREAD_CREATE_JOINABLE`, then the thread exit status and resources will be saved until the thread is joined by another thread (default).

# Thread Creation and Joining



# Thread Attributes

- Stack Address
  - The stack address specifies the base address of the stack for the thread.
  - After creating an attribute object (eg. attr), the stack address is set by  
`pthread_attr_setstackaddr()`
  - The stack address may be defined, but with care!
  - If stack address is defined `NULL`, then the system defines a stack address for the thread (default).

# Thread Attributes

- Stack Size

- The stack size specifies the size of the stack, in bytes, for the thread.
- After creating an attribute object (eg. attr), the stack address is set by  
`pthread_attr_setstacksize()`
- The stack address may be defined to a given value greater than `PTHREAD_STACK_MIN` bytes.
- If stack size is defined `NULL`, then stack size is set to the system default (default).

# Simple Thread Creation

## **Solaris**

```
(void *) foo(int arg);  
int arg;  
thr_create(NULL, NULL, foo, (void *) arg, NULL, NULL);
```

## **pthread**

```
(void *) foo(int arg);  
int arg;  
pthread_create(NULL, NULL, foo, (void *) arg);
```

# Simple Thread Creation

## OS/2

```
VOID foo(ULONG arg);  
ULONG arg;  
TID ThreadID;  
ULONG stacksize = 0x500;  
DosCreateThread(&ThreadID, (PFNTHREAD) foo, arg, NULL, stacksize);
```

## Windows NT

```
DWORD foo(DWORD arg);  
DWORD arg;  
DWORD ThreadID;  
CreateThread(NULL, NULL, (LPTHREAD_START_ROUTINE) foo,  
    (LPVOID) arg, NULL, &ThreadID);
```

# Solaris Threads and Pthreads

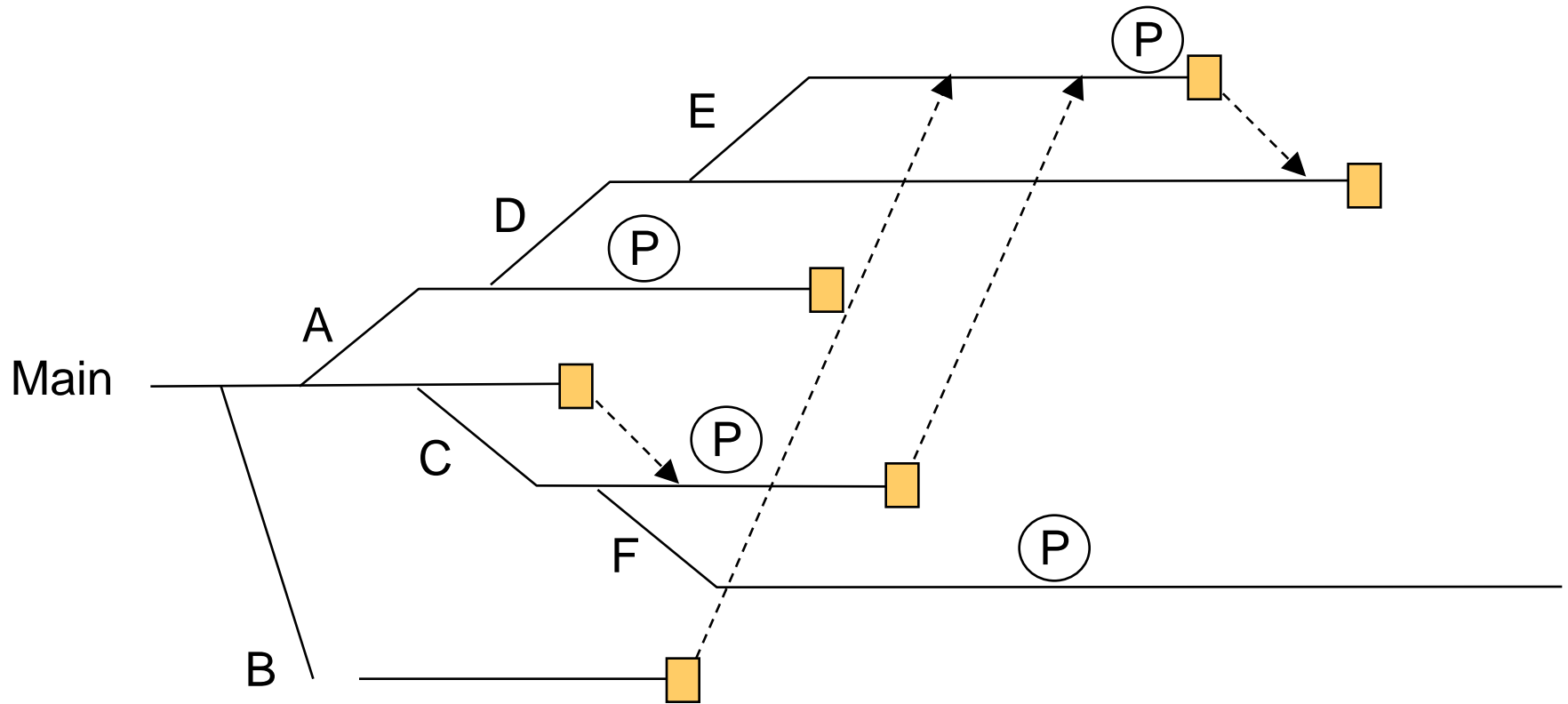
## **Solaris**

- Reader/writer locks (many readers, single writer)
- Ability to suspend and continue a single thread
- Ability to create daemon threads
- Ability to set and get a level of concurrency

## **Pthreads**

- Ability to cancel threads
- Attribute objects (thread and synchronization attributes)
- Scheduling policies

# Thread Creation and Joining



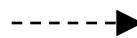
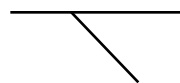
Thread

Thr\_create

thr\_join

thr\_exit

processing





# Thread Creation and Joining

- There is no parent/child relationship between threads as there is for processes.
- Threads can be created and joined by many different threads in the process
- In the example
  - Main thread creates A, B and C, then exits
  - Thread B is created suspended
  - Main thread exits with *thr\_exit()*, not *exit()* (which would have ended the whole process)
  - Main thread's exit status and resources are held until it is joined by thread C

# Thread Create and Join Example

## Variable initialization

```
#define _REENTRANT
#include <stdio.h>
#include <thread.h>

/ * Function prototypes for thread routines */
void *sub_a(void *);
void *sub_b(void *);
void *sub_c(void *);
void *sub_d(void *);
void *sub_e(void *);
void *sub_f(void *);

thread_t thr_a, thr_b, thr__c;
```

# Thread Create and Join Example

## Main thread

```
void main()
{
    thread_t main_thr;

    main_thr = thr_self(); /* returns thread ID for self */
    printf("Main thread = %d\n", main_thr);

    if (thr_create(NULL, 0, sub_b, NULL, THR_SUSPENDED|THR_NEW_LWP,
        &thr__b))
        fprintf(stderr, "Can't create thr_b\n"), exit(1);

    if (thr_create(NULL, 0, sub_a, (void *)thr_b, THR_HEW_LWP,
        &thr_a))
        fprintf(stderr, "Can't create fchr_a\n"), exit(1);
```

# Thread Create and Join Example

## Main thread

```
if (thr_create(NULL, 0, sub_c, (void *)main_thr, THR_NEW_LWP,
&thr_c))
    fprintf(stderr, "Can't create thr_c\n"), exit(1) ;

printf("Main Created threads A:%d B:%d C:%d\n", thr_a, thr_b,
thr_c) ;
printf("Main Thread exiting...\n");

thr_exit((void *)main_thr) ;
}
```

# Thread Create and Join Example

## Thread A

```
void *sub_a(void *arg)
{
    thread_t thr_b = (thread_t) arg;
    thread_t thr_d;
    int i;

    printf("A: In thread A...\n");

    if (thr_create(NULL, 0, sub_d, (void*)thr_b, THR_NEW_LWP,
        &thr_d))
        fprintf(stderr, "Can't create thr_d\n"), exit(1);
```

Thread A immediately creates thread D

# Thread Create and Join Example

## Thread A

```
printf("A: Created thread D:%d\n", thr_d);

/* process
*/
for ( i=0; i<1000000*(int)thr_self 0; i++ ) ;

    printf("A: Thread exiting...\n") ;

thr_exit((void *)77) ;

}
```

On exit, Thread A resources are reclaimed by the OS, since it was created with the `THR_DETACHED` flag.

# Thread Create and Join Example

## Thread B

```
void * sub_b(void *arg)
{
    int i;
    printf("B: In thread B...\n");

    /* process
    */

    for ( i=0; i<1000000*(int)thr_self(); i++ ) ;
        printf("B: Thread exiting...\n") ;
    thr_exit((void *)66);
}
```

Thread B was created suspended, so it runs only when thread D continues it with `thr_continue()`

# Thread Create and Join Example

## Thread C

```
void * sub__c(void *arg)
{
void *status;
int i;
thread_t main_thr, ret_thr;

main_thr = (thread_t)arg;

printf("C: In thread C...\n");

if (thr_create(NULL, 0, sub_f, (void *)0, THR_BOUND|THR_DAEMON,
NULL))
    fprintf(stderr, "Can't create thr_f\n"), exit(1);
```

Thread C creates thread F, then joins the main thread...



# Thread Create and Join Example

## Thread C

```
printf("C: Join main thread\n");

if (thr_join(main_thr, (thread_t *)&ret_thr, &status))
    fprintf(stderr, "thr_join Error\n"), exit(1);

printf("C: Main thread (%d) returned thread (%d) w/status
%d\n",
main_thr, ret_thr, (int) status);

/* simulated processing
*/
for ( i=0; i<1000000*(int)thr_self(); i++ ) ;

printf("C: Thread exiting...\n") ;
thr_exit((void *)88);
}
```

# Thread Create and Join Example

## Thread D

```
void * sub_d(void *arg)
{
    thread_t thr_b = (thread_t) arg;
    int i ;
    thread_t thr_e, ret_thr;
    void *status;

    printf('D: In thread D...\n');

    if (thr_create(NULL, 0, sub_e, NULL, THR_NEW_LWP, &thr_e))
        fprintf(stderr, "Can't create thr_e\n"), exit(1);

    printf("D: Created thread E:%d\n", thr_e);
```

Thread D creates thread E,

# Thread Create and Join Example

## Thread D

```
printf("D: Continue B thread = %d\n", thr_b) ;  
thr_continue(thr_b) ;  
  
printf("D: Join E thread\n");  
  
if(thr_join(thr_e, (thread_t *) &ret_thr, &status))  
    fprintf(stderr, "thr_join Error\n"), exit(1);
```

Thread D continues thread B by making `thr_continue()` call, then tries to join thread E, blocking until thread E has exited.

# Thread Create and Join Example

## Thread D

```
printf("D: E thread (%d) returned thread (%d) w/status %d\n",
thr_e,
ret_thr, (int) status);

/* simulated processing
*/
for ( i=0; i<1000000 *(int)thr_self(); i++ );

printf("D: Thread exiting ... \n");
thr_exit((void *)55);
}
```

Thread D should be the last non-daemon thread running. When it exits, it should stop the daemon thread and stop execution of the process.

# Thread Create and Join Example

## Thread E

```
void * sub_e(void *arg)
{
    int i ;
    thread_t ret_thr;
    void *status;

    printf("E: In thread E...\n");

    printf("E: Join A Chread\n");

    if(thr_join(thr__a, (thread_t *)&ret_thr, &status))
        fprintf(stderr, "thr_join Error\n"), exit(1) ;

    printf("E:A thread (%d) returned thread (%d) w/status %d\n",
        ret_thr, ret_thr, (int) status);
}
```

# Thread Create and Join Example

## Thread E

```
printf("E: Join B thread\n");
if(thr_join(thr_b, (thread_t *)&ret_thr, &status))
    fprintf(stderr, "thr_join Error\n"), exit(1);

printf("E: B thread (%d) returned thread (%d) w/status %d\n",
thr_b,
ret_thr, (int) status) ;

printf("E: Join C thread\n" ) ;

if(thr_join(thr_c, (thread_t *)&ret_thr, & status))
    fprintf(stderr, "thr_join Error\n"), exit(1) ;
```

Thread E tries to join threads B and C, waiting for each of these threads to exit.

# Thread Create and Join Example

## Thread E

```
printf("E: C thread (%d) returned thread (%d) w/status %d\n" ,  
thr_c,  
ret_thr, (int) ystatus) ;  
  
/* simulated processing  
*/  
for ( i=0; i<1000000*(int)thr_self(); i++);  
  
printf("E: Thread exiting...\n"),  
thr_exit((void *)-44);  
}
```

Then thread E exits, holding its resources until joined by thread D.

# Thread Create and Join Example

## Thread F

```
void *sub_f(void *arg)
{
int i;

printf("F: In thread F...\n");

while (1) {
    for (i=0, -i< 10000000, -i++) ;
    printf("F: Thread F is still running...\n") ;
}
}
```

Thread F was created as a bound daemon thread, running on its own LWP until all the nondaemon threads have exited the process.

- useful for background processing